

Amendments to the Specification:

The paragraph starting at page 1, line 23, is amended and now reads as follows:

-- The spring arrangement of the invention includes: a plurality of spring and shock absorber assemblies; each of the springs of the assemblies having first and second end positions (h_1, h_2) and being characterized by a maximum spring deflection ($\Delta h = h_2 - h_1$); a level control unit assigned to the springs of the assemblies; sensor means operatively connected to corresponding ones of the springs; the level control unit and the sensor means coacting to determine and adjust the spring elevation (h_x) between the first and second end positions; the shock absorbers of the assemblies having respective coefficients of friction (ρ_x); a shock absorber control unit connected to the shock absorbers of corresponding ones of the assemblies to adjust the damping hardness given by the corresponding coefficient of friction (ρ_x); and, the friction coefficient (ρ_x) of each one of the shock absorbers being a function of the spring elevation (h_x) measured for the spring associated therewith $[(\rho_x = f(h_x))]$
 $(\rho_x) = f(h_x)$. --

The paragraph starting at page 6, line 13, is amended and now reads as follows:

-- To control the damping force, the signals outputted by the damper control 34 and the end-position control 40 are outputted

to the damper actuating member 36. With the aid of the
end-position ~~control 38~~ control 40 according to the invention, an
end-position ~~buffer 40~~ buffer 38 (see FIG. 2) can be omitted. --